



DPDK

DATA PLANE DEVELOPMENT KIT

Platform Specific Guides

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The following are platform specific guides and setup information.

NXP QORIQ DPAA BOARD SUPPORT PACKAGE

This doc has information about steps to setup QorIQ dpaa based layerscape platform and information about common offload hw block drivers of **NXP QorIQ DPAA** SoC family.

1.1 Supported DPAA SoCs

- LS1046A/LS1026A
- LS1043A/LS1023A

More information about SoC can be found at [NXP Official Website](#).

1.2 Common Offload HW Block Drivers

1. Nics Driver

See `../nics/dpaa` for NXP dpaa nic driver information.

2. Cryptodev Driver

See `../cryptodevs/dpaa_sec` for NXP dpaa cryptodev driver information.

3. Eventdev Driver

See `../eventdevs/dpaa` for NXP dpaa eventdev driver information.

1.3 Steps To Setup Platform

There are four main pre-requisites for executing DPAA PMD on a DPAA compatible board:

1. ARM 64 Tool Chain

For example, the `*aarch64*` [Linaro Toolchain](#).

2. Linux Kernel

It can be obtained from [NXP's Github hosting](#).

3. Rootfile system

Any `aarch64` supporting filesystem can be used. For example, Ubuntu 16.04 LTS (Xenial) or 18.04 (Bionic) userland which can be obtained from [here](#).

4. FMC Tool

Before any DPDK application can be executed, the Frame Manager Configuration Tool (FMC) need to be executed to set the configurations of the queues. This includes the queue state, RSS and other policies. This tool can be obtained from [NXP \(Freescale\) Public Git Repository](#).

This tool needs configuration files which are available in the [DPDK Extra Scripts](#), described below for DPDK usages.

As an alternative method, DPAA PMD can also be executed using images provided as part of SDK from NXP. The SDK includes all the above prerequisites necessary to bring up a DPAA board.

The following dependencies are not part of DPDK and must be installed separately:

- **NXP Linux SDK**

NXP Linux software development kit (SDK) includes support for family of QorIQ® ARM-Architecture-based system on chip (SoC) processors and corresponding boards.

It includes the Linux board support packages (BSPs) for NXP SoCs, a fully operational tool chain, kernel and board specific modules.

SDK and related information can be obtained from: [NXP QorIQ SDK](#).

- **DPDK Extra Scripts**

DPAA based resources can be configured easily with the help of ready scripts as provided in the DPDK Extra repository.

[DPDK Extras Scripts](#).

Currently supported by DPDK:

- NXP SDK **2.0+** (preferred: LSDK 18.09).
- Supported architectures: **arm64 LE**.
- Follow the DPDK Getting Started Guide for Linux to setup the basic DPDK environment.

NXP QORIQ DPAA2 BOARD SUPPORT PACKAGE

This doc has information about steps to setup NXP QorIQ DPAA2 platform and information about common offload hw block drivers of **NXP QorIQ DPAA2** SoC family.

2.1 Supported DPAA2 SoCs

- LX2160A
- LS2084A/LS2044A
- LS2088A/LS2048A
- LS1088A/LS1048A

More information about SoC can be found at [NXP Official Website](#).

2.2 Common Offload HW Block Drivers

1. Nics Driver

See `../nics/dpaa2` for NXP dpaa2 nic driver information.

2. Cryptodev Driver

See `../cryptodevs/dpaa2_sec` for NXP dpaa2 cryptodev driver information.

3. Eventdev Driver

See `../eventdevs/dpaa2` for NXP dpaa2 eventdev driver information.

4. Rawdev AIOP CMDIF Driver

See `../rawdevs/dpaa2_cmdif` for NXP dpaa2 AIOP command interface driver information.

5. Rawdev QDMA Driver

See `../rawdevs/dpaa2_qdma` for NXP dpaa2 QDMA driver information.

2.3 Steps To Setup Platform

There are four main pre-requisites for executing DPAA2 PMD on a DPAA2 compatible board:

1. ARM 64 Tool Chain

For example, the [*aarch64* Linaro Toolchain](#).

2. Linux Kernel

It can be obtained from [NXP's Github hosting](#).

3. Rootfile system

Any *aarch64* supporting filesystem can be used. For example, Ubuntu 16.04 LTS (Xenial) or 18.04 (Bionic) userland which can be obtained from [here](#).

4. Resource Scripts

DPAA2 based resources can be configured easily with the help of ready scripts as provided in the DPDK Extra repository.

As an alternative method, DPAA2 PMD can also be executed using images provided as part of SDK from NXP. The SDK includes all the above prerequisites necessary to bring up a DPAA2 board.

The following dependencies are not part of DPDK and must be installed separately:

- **NXP Linux SDK**

NXP Linux software development kit (SDK) includes support for family of QorIQ® ARM-Architecture-based system on chip (SoC) processors and corresponding boards.

It includes the Linux board support packages (BSPs) for NXP SoCs, a fully operational tool chain, kernel and board specific modules.

SDK and related information can be obtained from: [NXP QorIQ SDK](#).

- **DPDK Extra Scripts**

DPAA2 based resources can be configured easily with the help of ready scripts as provided in the DPDK Extra repository.

[DPDK Extras Scripts](#).

Currently supported by DPDK:

- NXP SDK **2.0+** (preferred: LSDK 18.09).
- MC Firmware version **10.10.0** and higher.
- Supported architectures: **arm64 LE**.
- Follow the DPDK Getting Started Guide for Linux to setup the basic DPDK environment.

OCTEON TX BOARD SUPPORT PACKAGE

This doc has information about steps to setup OCTEON TX platform and information about common offload hw block drivers of **Cavium OCTEON TX** SoC family.

More information about SoC can be found at [Cavium, Inc Official Website](#).

3.1 Common Offload HW Block Drivers

1. **Crypto Driver** See `../cryptodevs/octeontx` for octeontx crypto driver information.
2. **Eventdev Driver** See `../eventdevs/octeontx` for octeontx ssovf eventdev driver information.
3. **Mempool Driver** See `../mempool/octeontx` for octeontx fpavf mempool driver information.

3.2 Steps To Setup Platform

There are three main pre-prerequisites for setting up Platform drivers on OCTEON TX compatible board:

1. **OCTEON TX Linux kernel PF driver for Network acceleration HW blocks**

The OCTEON TX Linux kernel drivers (includes the required PF driver for the Platform drivers) are available on Github at [octeontx-kmod](#) along with build, install and dpdk usage instructions.

Note: The PF driver and the required microcode for the crypto offload block will be available with OCTEON TX SDK only. So for using crypto offload, follow the steps mentioned in [Setup Platform Using OCTEON TX SDK](#).

2. **ARM64 Tool Chain**

For example, the `aarch64` Linaro Toolchain, which can be obtained from [here](#).

3. **Rootfile system**

Any `aarch64` supporting filesystem can be used. For example, Ubuntu 15.10 (Wily) or 16.04 LTS (Xenial) userland which can be obtained from <http://cdimage.ubuntu.com/ubuntu-base/releases/16.04/release/ubuntu-base-16.04.1-base-arm64.tar.gz>.

As an alternative method, Platform drivers can also be executed using images provided as part of SDK from Cavium. The SDK includes all the above prerequisites necessary to bring up a OCTEON TX board. Please refer [Setup Platform Using OCTEON TX SDK](#).

- Follow the DPDK `../linux_gsg/index` to setup the basic DPDK environment.

3.3 Setup Platform Using OCTEON TX SDK

The OCTEON TX platform drivers can be compiled either natively on **OCTEON TX**® board or cross-compiled on an x86 based platform.

The **OCTEON TX**® board must be running the linux kernel based on OCTEON TX SDK 6.2.0 patch 3. In this, the PF drivers for all hardware offload blocks are already built in.

3.3.1 Native Compilation

If the kernel and modules are cross-compiled and copied to the target board, some intermediate binaries required for native build would be missing on the target board. To make sure all the required binaries are available in the native architecture, the linux sources need to be compiled once natively.

```
cd /lib/modules/$(uname -r)/source
make menuconfig
make
```

The above steps would rebuild the modules and the required intermediate binaries. Once the target is ready for native compilation, the OCTEON TX platform drivers can be compiled with the following steps,

```
cd <dpdk directory>
make config T=arm64-thunderx-linuxapp-gcc
make
```

The example applications can be compiled using the following:

```
cd <dpdk directory>
export RTE_SDK=$PWD
export RTE_TARGET=build
cd examples/<application>
make
```

3.3.2 Cross Compilation

The DPDK applications can be cross-compiled on any x86 based platform. The OCTEON TX SDK need to be installed on the build system. The SDK package will provide the required toolchain etc.

Refer to `../linux_gsg/cross_build_dpdk_for_arm64` for further steps on compilation. The 'host' & 'CC' to be used in the commands would change, in addition to the paths to which libnuma related files have to be copied.

The following steps can be used to perform cross-compilation with OCTEON TX SDK 6.2.0 patch 3:

```
cd <sdk_install_dir>
source env-setup

git clone https://github.com/numactl/numactl.git
cd numactl
git checkout v2.0.11 -b v2.0.11
./autogen.sh
autoconf -i
./configure --host=aarch64-thunderx-linux CC=aarch64-thunderx-linux-gnu-gcc --prefix=<numa_inst
make install
```

The above steps will prepare build system with numa additions. Now this build system can be used to build applications for **OCTEON TX[®]** platforms.

```
cd <dpdk_directory>
export RTE_SDK=$PWD
export RTE_KERNELDIR=$THUNDER_ROOT/linux/kernel/linux
make config T=arm64-thunderx-linuxapp-gcc
make -j CROSS=aarch64-thunderx-linux-gnu- CONFIG_RTE_KNI_KMOD=n CONFIG_RTE_EAL_IGB_UIO=n EXTRA_
```

If NUMA support is not required, it can be disabled as explained in `../linux_gsg/cross_build_dpdk_for_arm64`.

Following steps could be used in that case.

```
make config T=arm64-thunderx-linuxapp-gcc
make CROSS=aarch64-thunderx-linux-gnu-
```

SDK and related information can be obtained from: [Cavium support site](#).